

# I/Q -Modulator Circuit for 7-Tesla MRI Smart Power Amplifier

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# Outline

- **Motivation**

why we need smart power amplifier?

how is the I/Q modulator constructed?

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how to verify their functionalities?

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  - how to handle so many passive and active elements?

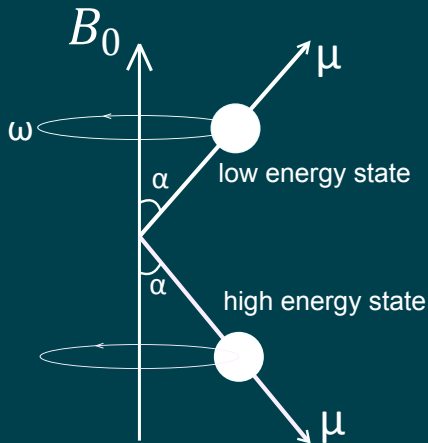
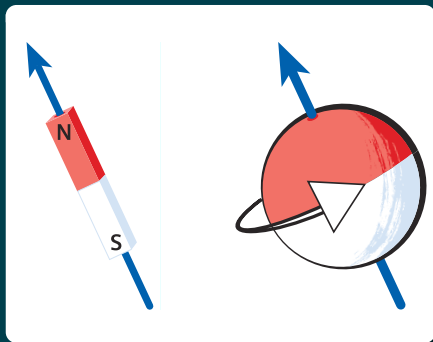
- **Circuit Test & Analysis**

  - how to verify their functionalities?

- **Conclusion**

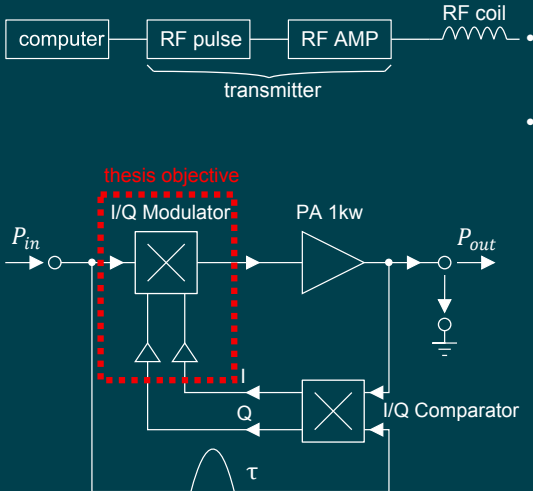
# Motivation I

## *Nuclear Magnetic Resonance*



# Motivation II

## RF Pulse Generation



- $f_{Larmor} = \frac{\gamma}{2\pi} B_0$ , e.g.  
 $f_{Larmor} \approx 298\text{MHz}$  at 7T

- **RF power amplifier linearization scheme**

- cartesian feedback
- carrier is I/Q modulated before power amplification. The distorted signal is then fed back through an I/Q demodulator. The separated I and Q components are fed back to perform the linearization.

# Motivation III

## *Thesis Task: I/Q Modulator Circuit*

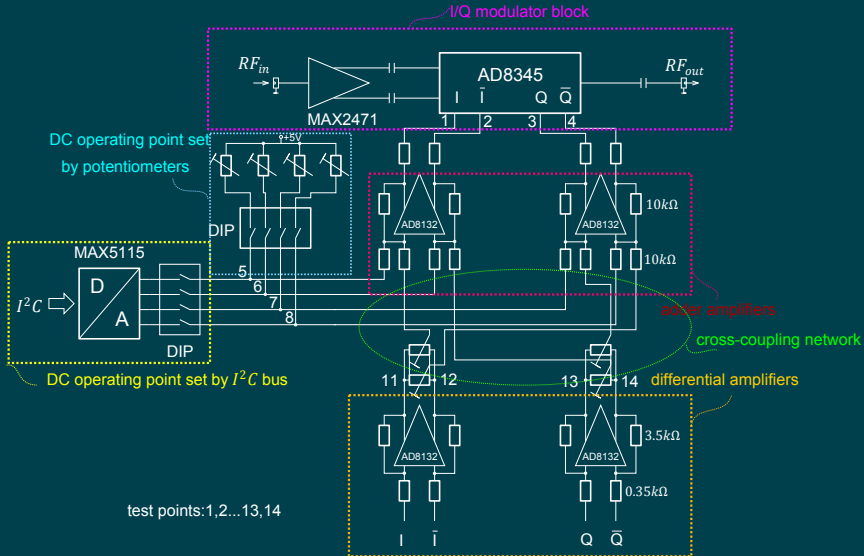
- **Functions to realise:**
  - I/Q Modulator
  - amplitude/phase control of baseband signals
  - DC operating point set of the modulator in 2 ways
- **How to realise?**

Answer: circuit modularization!



# Motivation IV

## Thesis Task: I/Q Modulator Circuit



# PCB Design & Theory

## *Design Methodology*

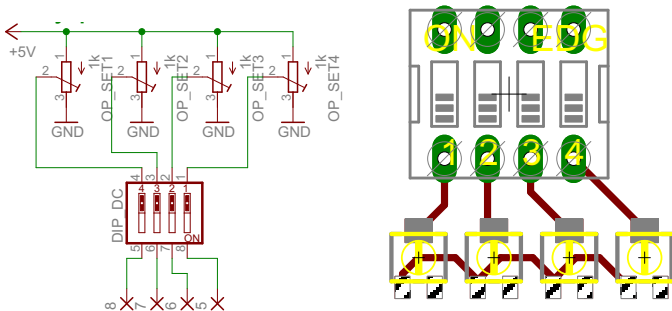
- **modular design: top down, bottom up**

modular programming is a programming style that breaks down program functions into independent, interchangeable modules

- **circuit modularization**
  - **DC operating point set**
    - by potentiometers
    - by DAC through I<sup>2</sup>C control
  - **Phase/amplitude adjustment**
    - differential amplifier
    - adder amplifier
    - cross-coupling
  - **I/Q modulator**

# DC Operating Point Set I

by potentiometers



- block isolation through DIP switch

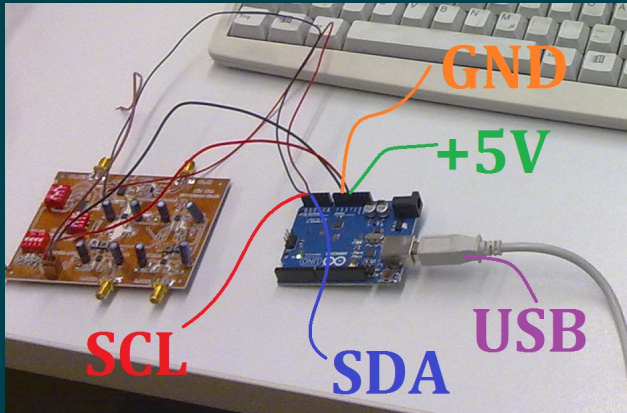
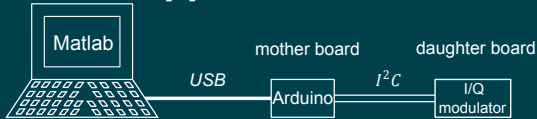
- advantage: isolation between function blocks
- disadvantage: cost extra PCB area

- 4 test pins designed for test



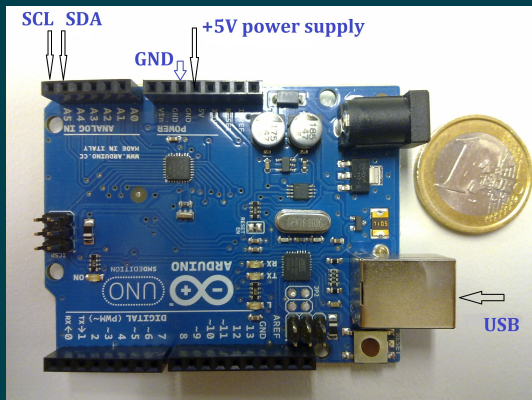
# DC Operating Point Set by I<sup>2</sup>C

## A Simple I<sup>2</sup>C Bus Application



# DC Operating Point Set by I<sup>2</sup>C

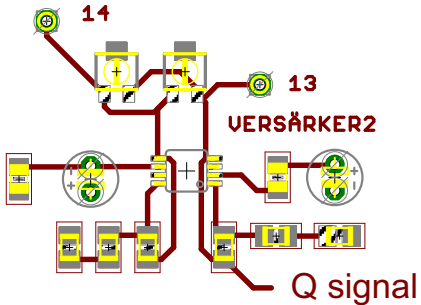
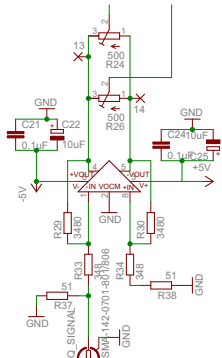
## The Arduino Platform



- open-source
- simple, cheap, easy to use
- Arduino “UNO”
  - powered through USB or external power source
  - communication through USB
- **ATTENTION:** mother board and daughter board should have the same GND level!

# Phase/Amplitude Adjustment I

## *differential amplifier*



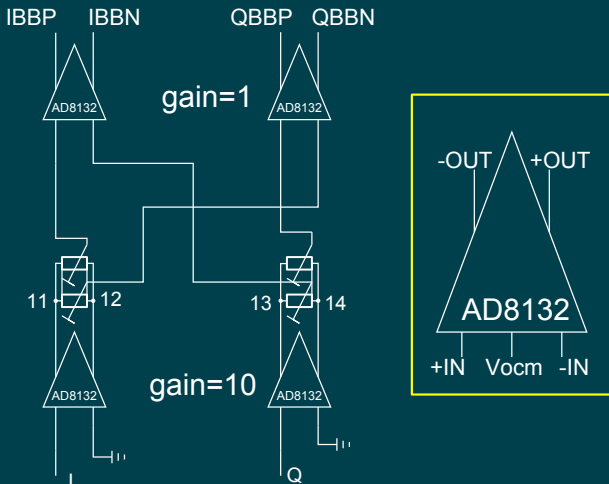
- 2 test points
- differential or single-ended input
- gain user defined
- symmetrical output
  - harmonics suppression
  - EMI reduction





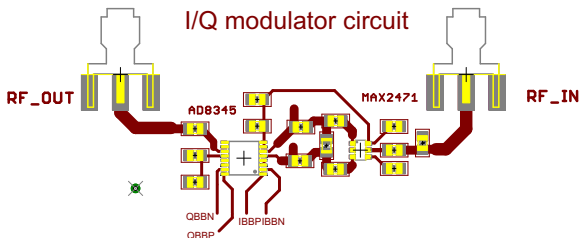
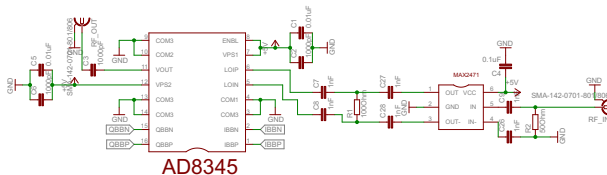
# Phase/Amplitude Adjustment III

## *cross-coupling*



- $I = \cos(t)$ ,  $Q = \sin(t)$
- $QBBP = -[m \cdot \sin(t) - n \cdot \cos(t)] = \sqrt{m^2 + n^2} \sin(t + \varphi)$   
 $m, n \in [-gain, +gain]$

# I/Q Modulator I



- no test points
- inputs and outputs of AD8345 and MAX2471 are AC coupled and terminated with 50Ω resistors
- MAX2471 acts as balun
  - signal conversion from assymetrical to symmetrical
  - immunity to external noises

# I/Q Modulator II

## S-parameter $\underline{S}_{21}$ Measurement

- $I = V_x, Q = V_{const}$

$$\underline{S}_{21} = \left. \frac{V_2^-}{V_1^+} \right|_{V_2^+ = 0} = \boxed{V_x e^{j0^\circ}} + V_{const} e^{j90^\circ}$$

- $I = V_{const}, Q = V_x$

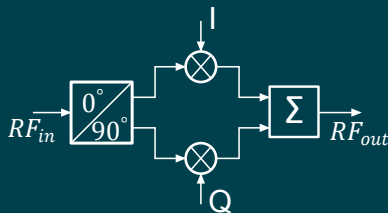
$$\underline{S}_{21} = \left. \frac{V_2^-}{V_1^+} \right|_{V_2^+ = 0} = \boxed{V_x e^{j90^\circ}} + V_{const} e^{j0^\circ}$$

- $I = \cos(V_x), Q = \cos(V_{DC} + 90^\circ) = -\sin(V_x)$

- $\underline{S}_{21} = \cos(V_x) e^{j0} - \sin(V_x) e^{j90^\circ}$

- $I = \text{Re} \{ A_1 e^{j(\omega_1 t + \varphi_0)} \}$ , and  $Q = \text{Re} \{ A_1 e^{j(\omega_1 t + \varphi_0 + 90^\circ)} \}$

- $\underline{S}_{21}$  doesn't exist any more because S-parameters are supposed to characterise linear networks



# I/Q Modulator III

## $S_{21}$ ADS Simulation

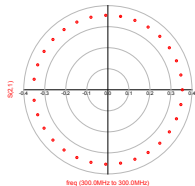
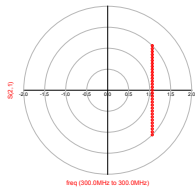
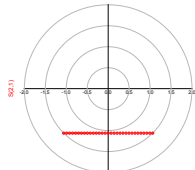
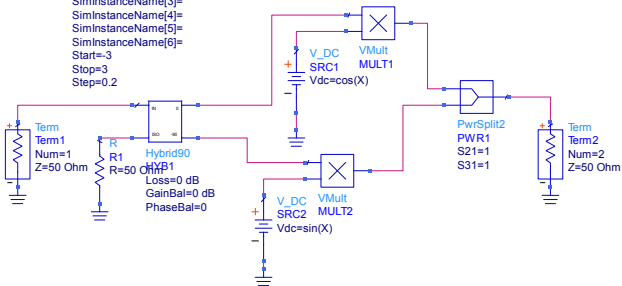
### PARAMETER SWEEP

ParamSweep  
Sweep1  
SweepVar="X"  
SimInstanceName[1]="SP1"  
SimInstanceName[2]=  
SimInstanceName[3]=  
SimInstanceName[4]=  
SimInstanceName[5]=  
SimInstanceName[6]=  
Start=-3  
Stop=3  
Step=0.2

Var  
Eqn. VAR  
VAR1  
X=1.0

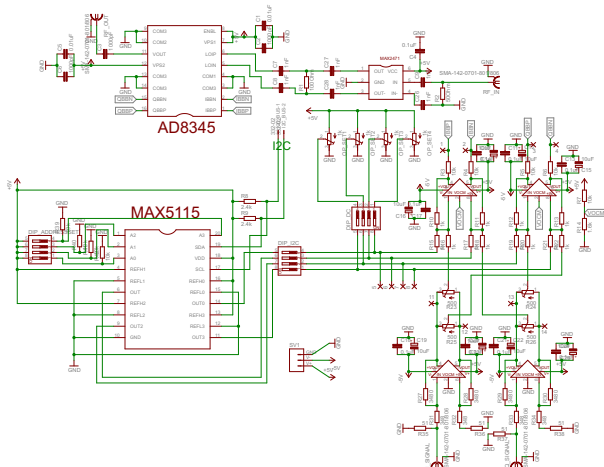
### S-PARAMETERS

S\_Param  
SP1  
Start=0.3 GHz  
Stop=0.3 GHz  
Step=1



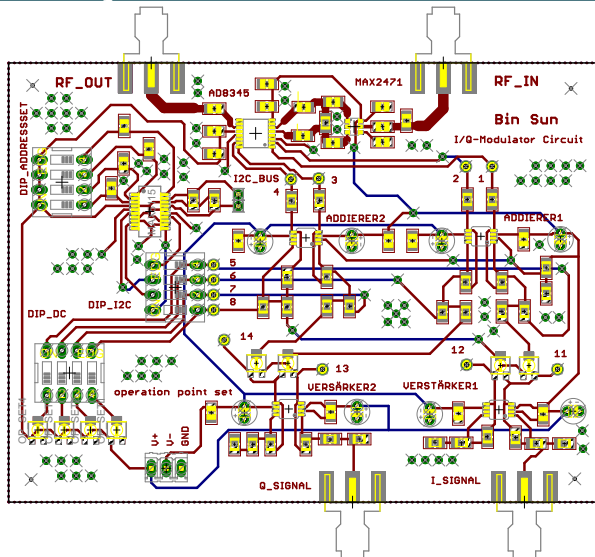
# Whole I/Q Modulator Circuit I

## Whole PCB Schematic



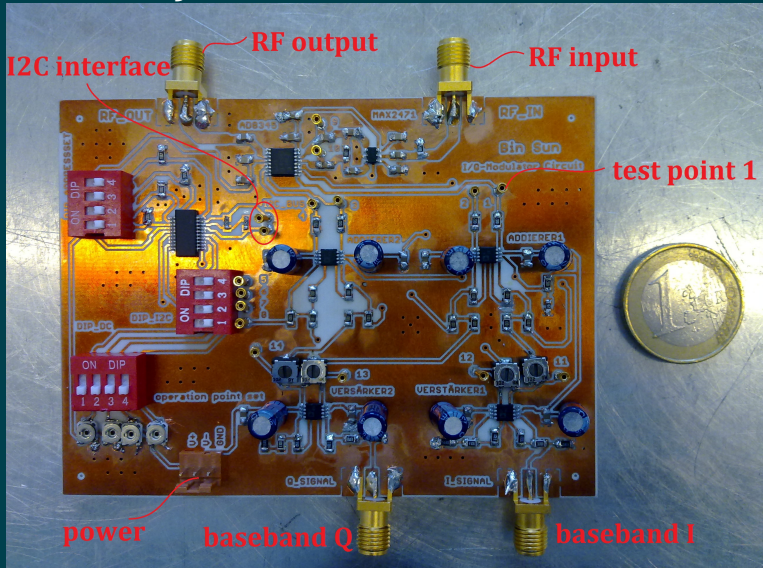
# Whole I/Q Modulator Circuit II

## Whole PCB Layout



# PCB Assembly

## PCB Assembly



# Circuit Test & Analysis I

## *DC current consumption of activ components*

| Element | DC Current Consumption | Amount | -5V Total | +5V Total |
|---------|------------------------|--------|-----------|-----------|
| AD8345  | 70mA                   | 1      |           |           |
| AD8132  | 12mA                   | 4      | 48mA      | 123.5mA   |
| MAX5115 | 200 $\mu$ A            | 1      |           |           |
| MAX2471 | 5.5mA                  | 1      |           |           |

Current consumption shown on the power suppliers:

- -5V: 0.04A~0.05A
- +5V: 0.12A~0.13A

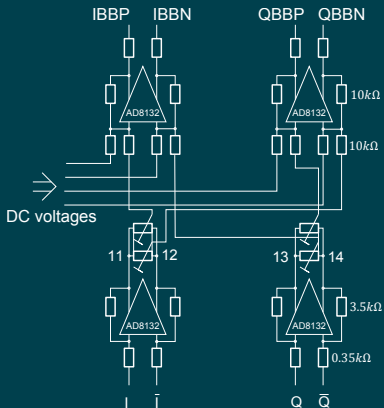
Potential problems:

- can only roughly evaluate the components
- for example if MAX5115 is not working, the current won't change magnificently

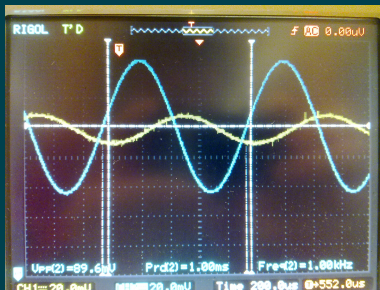
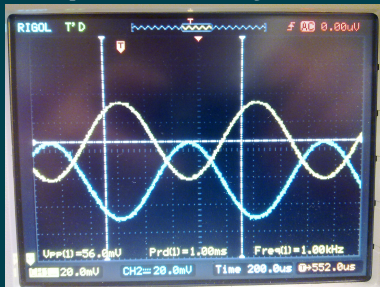


# Circuit Test & Analysis II

## Functionality of the Phase/Amplitude Adjustment Circuit

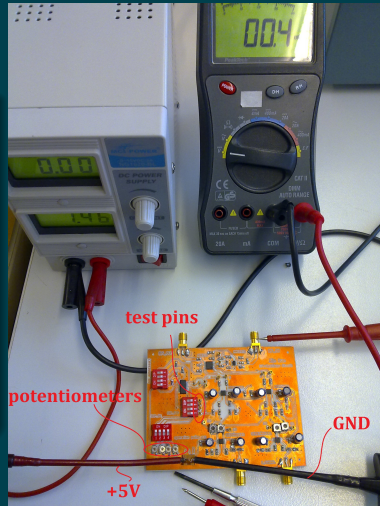
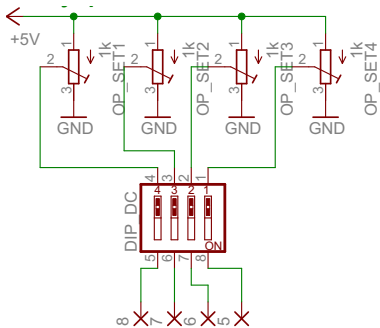


- $I = 50\text{mV} \cos(2\pi 1000\text{Hz})$
- $Q = -50\text{mV} \sin(2\pi 1000\text{Hz})$



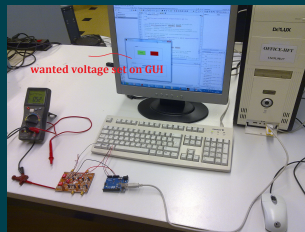
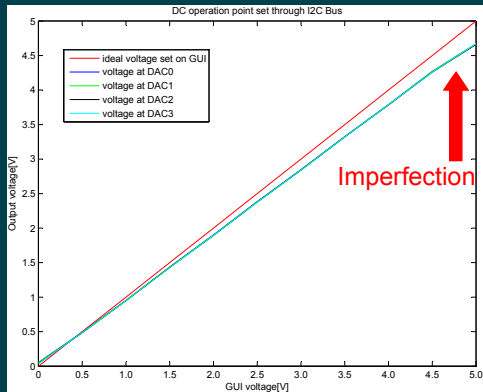
# Circuit Test & Analysis III

## Functionality of the DC operating point set by potentiometers



# Circuit Test & Analysis IV

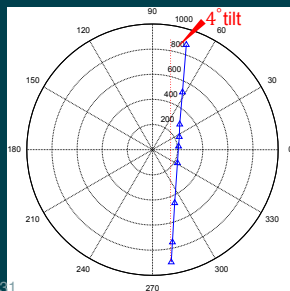
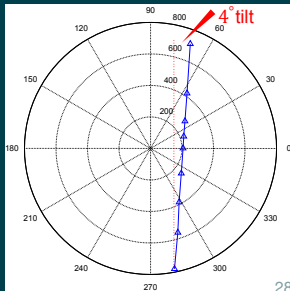
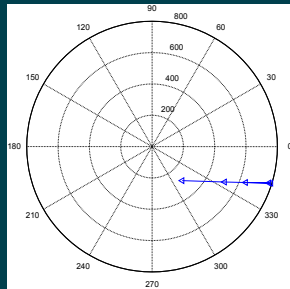
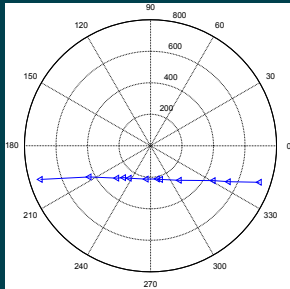
## Functionality of the DC operating point set by DAC



- error become larger when voltage increases
  - voltage is not exact +5V when powered by USB
  - solution: use lab power supply

# Circuit Test & Analysis V

## RF Functionality of the IQ Modulator



# Circuit Test & Analysis VI

## RF Functionality of the IQ Modulator



# Conclusion

## *Thesis summary*

- **circuit modularization**
  - ✓ simplify the routing task
  - ✓ provide isolation between function blocks
  - × cost extra PCB material
- **future work**
  - **DAC output voltage imperfection**  
power the Arduino board through external power source between 7V~12V instead of USB
  - **I/Q modulator imperfection**
    - design the microstrip lines even shorter
    - symmetrical outputs of circuits equal in length

**Thank you for your  
attention!**

**Questions?**